## HE3B Series Pushbutton Enabling Switch

HE3B Key features include:

- 3 position funtionality (OFF - ON - OFF) as required for manual robotic control
- Provides a high level of safety based on human behavioral studies that determine personnel may squeeze OR let go when presented with a panic situation
- Contacts will not re-close when released frolm@ff(B] 1) (per IEC60204-1; 9.2.5.8)
- Multiple contacts for enhanced reliability
- Snap acting contacts from position 1 to 2
- Available with or without rubber cover

Specifications

| Conforming to Standards | IEC60947-5-1, EN60947-5-1, JIS C8201-5-1, UL508, CSA C22.2 No 14 |
| :--- | :--- |
| Application Standards | ISO12100/EN292, IEC60204-1/EN60204-1, ISO11161/prEN11161, <br> ISO10218/EN775, ANSI/RIA R15.06 |
| Operating Temperature | -25 to $+60^{\circ} \mathrm{C}$ (no freezing) |

## Part Numbers



## Contact Ratings

| Rated Insulation Voltage (Ui) |  |  | 125 V |  |
| :---: | :---: | :---: | :---: | :---: |
| Thermal Current (Ith) |  |  | 3A |  |
| Rated Operating Voltage (Ue) |  |  | 30V | 125 V |
| Rated Operating Current (le) | AC | Resistive Load (AC-12) | - | 1A |
|  |  | Inductive Load (AC-15) | - | 0.7A |
|  | DC | Resistive Load (DC-12) | 1A | 0.2A |
|  |  | Inductive Load (DC-13) | 0.7A | 0.1 A |
| Contact Structure (3 Position Switch) |  |  | 2 contacts (DPDT) |  |

## Circuit Diagrams

## Terminal Circuit Diagrams (bottom view)



1. 3 position switch: 2 contacts, terminal no. = between NO1-C1, between NO2-C2
2. Use between NO-C for OFF $\rightarrow \mathrm{On} \rightarrow \mathrm{OFF} 3$ position switch (NC is not used).

3. Use a lock nut tool to screw on the lock nut (see page 412).
4. To retain the switches waterproof performance, do not penetrate the rubber cover
5. Remove the rubber cover projection if you do not want a positioning hole. (Do not penetrate the rubber cover)

## Operating Characteristics

## Operating Characteristics (without rubber cover/pushing button part A and B)

Position 3


Notes:

- When rubber boot is used, operating force depends on the operating temperature.

Dimensions (mm)
Without Rubber Cover


Accessories
Replacement Rubber Cover

| Appearance | Color | Part Number | Material |
| :---: | :---: | :---: | :---: |
|  | Yellow | HE9Z-D3Y |  |
|  |  |  | Silicon <br> Rubber |
|  | Black | HE9Z-D3B |  |

With Rubber Cover


All dimensions in mm.

## General Information

## Safety Precautions

- In order to avoid electric shock or fire, turn power off before installation, removal, wire connection, maintenance or inspection of switch.
- Follow specification when installing. Improper electrical load may damage switch, cause electric shock, or fire.
- Use proper wire diameter to meet voltage and current requirements. Using improper wires or incomplete soldering may cause fire due to abnormal heat generation.
- If the panel is not level when mounting an enabling switch, the waterproof feature cannot be guaranteed.


## HE3B

- The rubber boot has a tab to be used for orientation. When making a positioning hole in a panel, do not make a hole in the rubber boot, or the waterproof feature cannot be guaranteed. When the positioning hole is not on the panel, remove the tab, but do not make a hole in the rubber boot.
- When tightening the locking ring, secure the flange to prevent the enabling switch from rotating. In applications where the enabling switch is to be rotated, mount the switch in a recess on the panel as shown.



## Wiring Precautions HE1B/HE2B/HE3B

- Applicable wire size is $0.5 \mathrm{~mm}^{2}$ (20AWG) (maximum) / 1 line.
- When soldering the terminal, solder at a temperature of $260^{\circ} \mathrm{C}$ within 3 seconds. Use non-corrosive liquid rosin as soldering flux.


## HE1G

- Wire Stripping Information
Wire Length
- Applicable Wire Size:0.14 to $1.5 \mathrm{~mm}^{2}$ (24-16AWG, one wire per terminal)


## Use Precautions <br> HE2B/HE3B/HE1G

- To ensure the highest level of reliability connect both contacts to a monitoring device such as a safety relay.
- Recommended Torque


|  | See Drawing Above | Recommended Torque |
| :---: | :---: | :---: |
| Rubber Boot \& Base | A | $1.2 \pm 0.1 \mathrm{Nm}$ |
| Connector \& Grip Switch | B | $4.0 \pm 0.3 \mathrm{Nm}$ |
| Connector | C | $4.0 \pm 0.3 \mathrm{Nm}$ |
| Terminal Screw | D | $0.5 \pm 0.6 \mathrm{Nm}$ |
| Do Not Remove | E |  |

